


Java Language and Tools for Realtime and Safety Critical Applications

The Challenges and Opportunities of Using Java Technology

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Java Technology for Realtime

When faced with ever more complex requirements, greater cost pressure, and rigorous certification,

the choice of languages matters!

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The Importance of Language

- Available Expertise
- Tools Support
- Available Libraries
- Code Generation
- Resource Efficiency
- Robustness
- Understandability
- Traceability
- Analyzability
- Reusability
- Modularity
- Consistency
- Completeness
- Soundness

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Language Types

- Specification languages
- Modelling languages
- Domain specific languages
- Programming languages
- Configuration languages
- Testing languages
- Byte and Machine Code

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Critical Systems Development in Flux

- Ada losing market relevance
 - Ever fewer qualified developers
 - Perceived as career dead end
 - Decreasing vendor support
- C and C++ popular but provide little programmer support
- Java technology is increasingly interesting
 - Tools support
 - Implementation for critical systems maturing

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Competitive Advantages of Java

- Time to Market
- Reliability
- Flexibility
 - Look and feel
 - Extensibility
- Reusability of code
- Platform independence

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Advantage of Java over C and C++

- Clean syntax and semantics w/o preprocessor
 - wide ranging and better tool support
- Better support for separating of subtyping and reuse via limited inheritance and interfaces
- No explicit pointer manipulation
- Pointer safe deallocation
- Single dispatch style
- Strong, extensible type system
- Well defined tasking model

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Risks of Using Java Technology

- High memory requirements
- Poor runtime performance
- Pauses during execution due to GC
 - Poor user interface feedback
 - Unpredictable execution time
- Undefined scheduling semantics
- No accurate clocks and timers
- Danger of priority inversion in shared code
- No direct hardware access

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Alleviating Risks of Java Technology

- Code Reduction
- Static Compiler Technology with Profiling
 - Faster Code
 - Better time vs. space trade off
- Real-Time Specification for Java
- Realtime Garbage Collection
- Safety Critical Java

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Reduction of Memory Demand


High memory demand of Java is mainly due to large libraries; but there are solutions.

- Reduction of the Java APIs through **configurations** and **profiles** (CLDC, CDC, etc.).
- Class file **compaction**
 - Use of a compact class format
 - Execution out of ROM

Typically saves 50% of the code size
- **Smart Linking**: removal of unused code

Typically saves 70-90% of the code size

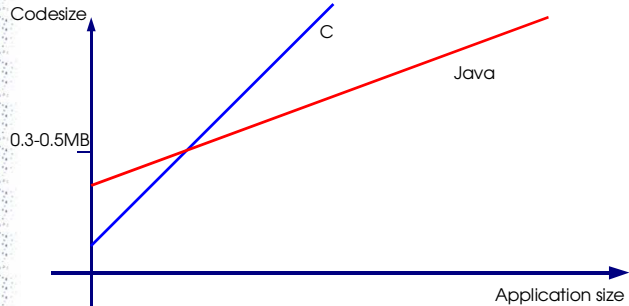
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Reduction of Memory Demand

Java bytecode is 2-3x smaller than compiled C Code!



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Execution Speed

Java interpreters are slow; **compiled code is faster, but**

- Just-in-Time Compilation
 - is not deterministic
- Load-time Compilation
 - has high memory demand on target system
- Static Compilation with Profiling
 - yields best results for small, closed systems.
 - Embedded VM for dynamic loaded code

Typical compilation speed up: **10-30 times faster**

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Real-Time Specification for Java (RTSJ)

- Extends Java for realtime programming
- Many new features to manage
 - Scheduling
 - Threads
 - Memory
 - Synchronization
 - Control Flow

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Realtime Scheduling

- New execution environment for Java
 - `RealtimeThreads`
 - `AsyncEventHandlers`
 - At least 28 additional realtime priorities
- Scheduler
 - `PriorityScheduler` is required as default
 - Fixed priority, preemptive scheduling
 - Both `RealtimeThread` and `AsyncEventHandler` are `Schedulable` objects

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Asynchronous Event Handlers

- Bind `Schedulable` object to an event for immediate processing upon reception
- Provides an additional processing paradigm besides `RealtimeThreads`
- Light weight (>10,000 possible)
- Executed in a thread context but need not be bound to one
- Easier to analyze

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Threads without GC

No-Heap version of schedulable objects:


- `NoHeapRealtimeThread`
- `AsyncEventHandler` with `noheap == true`

Only no-heap versions are guaranteed not to be interrupted by garbage collection.

No-heap threads and event handlers must not access heap.

Runtime checks enforce this by throwing an `IllegalAccessError` if a heap object is used.

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Memory Areas

MemoryArea abstracted from the heap to generalize the concept of allocation context.


HeapMemory

- default allocation context
- controlled by GC
- not accessible by non-heap schedulable objects

ImmortalMemory

- default allocation context for static initializers
- memory is never reclaimed
- accessible by all schedulable objects

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Memory Reclamation without GC


ScopedMemory

- region based memory management
- only active if entered explicitly
- memory is reclaimed automatically when exited

Avoiding dangling and false references

- assignment rules prohibit creation of potential dangling references:
 $a.f = b$
 for b in scope s is allowed only if a is in the same scope or in an inner scope of s .
- **IllegalAssignmentError** if assignment rule violated

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Access to Physical Memory

- **RawMemoryAccess** for getting and setting bytes of physical memory
 - Reading memory mapped sensors
 - Device control
- **LTPhysicalMemory** and **VTPhysicalMemory** for mapping Java object to special memory areas
 - Make special memory available for Java objects, e.g. fast memory.

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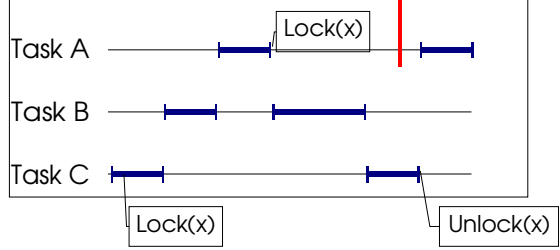


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Synchronization

Priority Inversion can be problematic

Deadline Task A missed!



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Synchronization

Priority Inheritance

Task A — Lock(x)

Task B —

Task C — Lock(x) — Unlock(x)

Deadline Task A

Priority Inheritance

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Synchronization

Priority Ceiling Emulation

Task A — Lock(x)

Task B —

Task C — Priority Ceiling — Lock(x) — Unlock(x)

Deadline Task A

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Priority Inheritance vs Priority Ceiling

Priority Inheritance

- + Does not need any user configuration
- Deadlock can occur

Priority Ceiling

- + Is inherently deadlock free
- Requires manual selection of ceiling priority
- may block threads more often than needed

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Deadline and Cost Monitoring

- Notification when deadline is missed or cost for thread is too high
- Enables program to take corrective action

Asynchronous Transfer of Control (ATC)

- Enables a thread to interrupt another thread by throwing an exception in the other threads context
- Terminates unneeded execution

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The Challenge: Garbage Collection

Garbage Collector

- needs to clean up memory for the user.

In classic Java systems

- Dedicated thread for GC
- Regularly stops the application for GC work

Consequences

- Difficult to predict memory demand
- Unpredictable pauses
- **No realtime or safety critical code possible!**

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Realtime Garbage Collection

- Paced garbage collector
 - Run GC at lower priority than realtime tasks
 - Scheduled to run at a given interval, for a given amount of time
 - Programmer must know both maximum memory use and maximum allocation rate
- Allocation time garbage collector
 - No GC thread; GC borrows application thread
 - Needs only maximum memory use

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Classic Garbage Collection

GC can interrupt execution for long periods of time:

Thread: → time

GC

User 1

User 2

...

Problem

long, unpredictable pauses during execution

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RTSJ with Classic Garbage Collection

No heap threads can interrupt garbage collector:

Thread: → time

rt1

rt2

GC


User 1

User 2

...

The application must be split into a realtime and a non-realtime part.

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Deterministic Garbage Collection

All Java threads are realtime threads:

Thread: → time

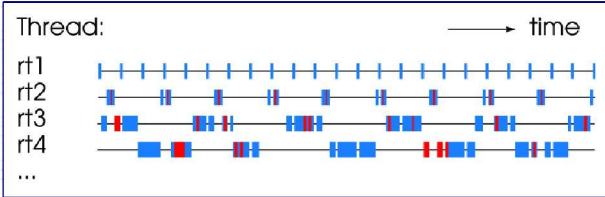
rt1

rt2

rt3


rt4

...



- GC work is performed at allocation time
- GC work must be sufficient to recycle enough memory before free memory is exhausted
- Execution time of all allocations must be bound

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RTSJ with Deterministic GC

- The RTSJ provides necessary features for realtime programming
- Memory area restrictions can be relaxed
 - Can use `RealtimeThread` instead of `NoHeapRealtimeThread`
 - Heap allocation possible in realtime code
 - Synchronization possible with non realtime tasks without GC interference
 - GC does not interrupt thread execution

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Safety Critical Java

Safety Critical Java (JSR 302)

- Java optimized for safety critical application, e.g. DO-178B levels A and B
- Based on a subset of the RTSJ
- Uses `ScopedMemory` for managing deallocation instead of garbage collection
- Uses extended typing through annotations to support static analysis
- Minimum set of supported classes

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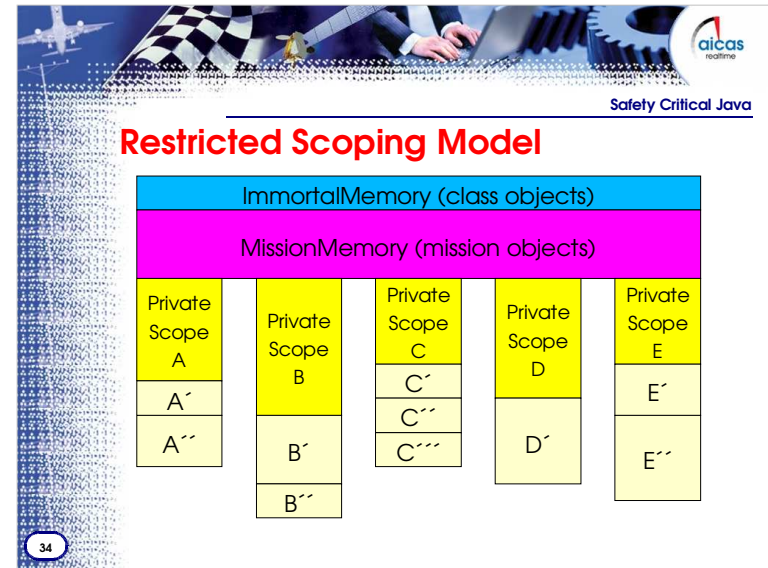
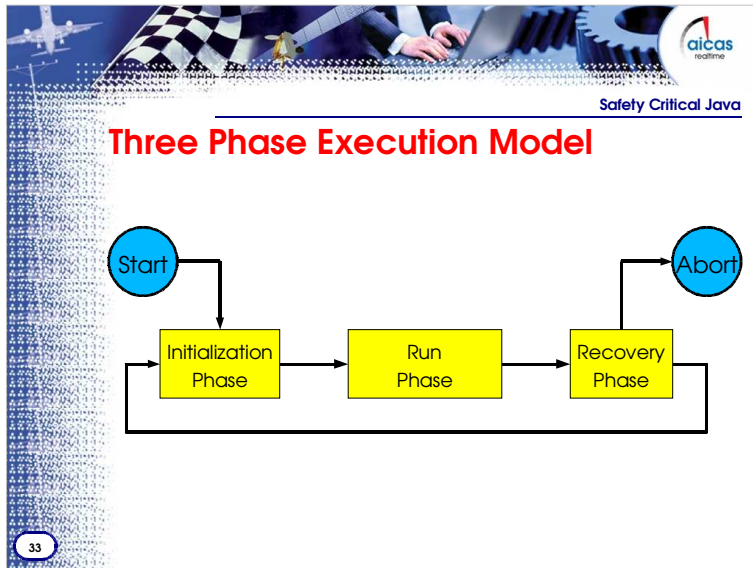


Safety Critical Java

Safety Critical Java (JSR 302)

- Immortal memory and single mission scope
 - Three phases execution: initialize, run, recovery
 - Mission scope entered before initialization and exited after recovery (reinitializable immortal)
 - Allocation in mission scope only during initialization
- Dedicated scope for each execution context
 - Entered before release and exited on completion
 - Only state using primitive types saved in objects in mission scope can survive between releases

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Safety Critical Java
- ## Possibly Three Levels
- Level 0
 - Cyclic Executive
 - No threading
 - Level 1
 - Single Mission
 - Limited synchronization
 - Level 2
 - Nested Missions
 - Flexible synchronization
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Safety Critical Java
- ## Certification Issues
- Class initialization
 - Dynamic dispatch
 - Garbage collection
 - Unchecked exceptions
 - Dynamic class loading
 - Just in time compilation
 - Reflection
 - Asynchronous transfer of control
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Support and Analysis Tools

- Debugging
- Refactoring
- Data Flow Analysis (DFA)
- Thread monitoring
- Deductive Functional Verification
- Model checking
- Worst case memory analysis
- Worst case execution time analysis

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Debugging and Monitoring in Java

The diagram illustrates the architecture for debugging and monitoring. On the left, the 'JamaicaVM Application' (Target) contains 'Standard Classes', 'JVM', and 'JVMTI Agent'. On the right, 'Eclipse' (Host) contains a 'Debugging Client'. A 'JDWP' (Java Debug Wire Protocol) connection is shown between the 'JVMTI Agent' in the Target and the 'Debugging Client' in the Host.

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Thread Monitor

The screenshot shows the 'Thread Monitor' interface. On the left, there is a 'Connect for Monitoring' window with fields for IP Address (127.0.0.1) and Port (7777). Below it is a list of threads with columns for 'waiting', 'ready', 'hired', and 'detached'. The main area displays a 'ThreadMonitor' window with a timeline showing thread execution. The timeline includes columns for 'expand time', 'contract time', 'zoom in', and 'zoom out'. The threads listed include 'RealtimeThreadImpl=1,apertid', 'RealtimeThreadImpl=11,apertid', 'RealtimeThreadImpl=6,apertid', 'RealtimeThreadImpl=4,apertid', 'RealtimeThreadImpl=12,apertid', 'RealtimeThreadImpl=9,apertid', 'SchedulerBvtAccordImpl=30', 'Finalizer', and 'main'. The timeline shows various states and transitions between threads over time.

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Data Flow Analysis

- Full program flow analysis
- Fixed point algorithm
- Can detect all possible runtime exceptions

Class cast	Illegal assignment
Array Store	Null pointer
Index out of bounds	Sync needed
Negative array size	Deadlock
Divide by zero	Illegal sync use
Scope cycle	Illegal wait use

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The JamaicaVM Solution

Detecting Runtime Errors


```
...
if (device instanceof MyDevice)
{
    MySensor s = (MySensor) device.sensor;

    int value = s.reading();

    ...
}
...
```

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The JamaicaVM Solution

Detecting Runtime Errors


```
...
if (device instanceof MyDevice)
{
    MySensor s = (MySensor) device.sensor;

    int value = s.reading();

    ...
}
...
```

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The JamaicaVM Solution

Detecting Runtime Errors


```
...
if (device instanceof MyDevice)
{
    MySensor s = (MySensor) device.sensor;

    int value = s.reading();

    ...
}
...
```

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The JamaicaVM Solution

Detecting Runtime Errors

```
...
if (device instanceof MyDevice)
{
    MySensor s = (MySensor) device.sensor;

    int value = s.reading();

    ...
}
...
```

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Detecting Runtime Errors

```

...
device != null
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  // NullPointerException
  // ClassCastException
  int value = s.reading();
  // NullPointerException
  ...
}
...

```

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Detecting Runtime Errors

```

...
device != null
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  // NullPointerException
  // ClassCastException
  int value = s.reading();
  // NullPointerException
  ...
}
...

```

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Detecting Runtime Errors

```

...
device != null
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  // NullPointerException ✓
  // ClassCastException
  int value = s.reading();
  // NullPointerException
  ...
}
...

```

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  // NullPointerException ✓
  // ClassCastException
  int value = s.reading();
  // NullPointerException
  ...
}
...

```

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 49:

- `device.sensor` is circled in green with a checkmark and labeled "NullPointerException ✓".
- `(MySensor)` is circled in red and labeled "ClassCastException".
- `s.reading()` is circled in red and labeled "NullPointerException".
- A note states: "values(MyDevice.sensor) contains only MySensor".

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 50:

- `device.sensor` is circled in green with a checkmark and labeled "NullPointerException ✓".
- `(MySensor)` is circled in red and labeled "ClassCastException".
- `s.reading()` is circled in red and labeled "NullPointerException".
- A note states: "values(MyDevice.sensor) contains only MySensor".

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 51:

- `device.sensor` is circled in green with a checkmark and labeled "NullPointerException ✓".
- `(MySensor)` is circled in green with a checkmark and labeled "ClassCastException ✓".
- `s.reading()` is circled in red and labeled "NullPointerException".
- A note states: "values(MyDevice.sensor) contains only MySensor".

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 52:

- `device.sensor` is circled in green with a checkmark and labeled "NullPointerException ✓".
- `(MySensor)` is circled in green with a checkmark and labeled "ClassCastException ✓".
- `s.reading()` is circled in red and labeled "NullPointerException".

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 53:

- `device.sensor`: `NullPointerException ✓` (green circle)
- `(MySensor)`: `ClassCastException ✓` (green circle)
- `s.reading()`: `NullPointerException` (red circle)

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 54:

- `device.sensor`: `NullPointerException ✓` (green circle)
- `(MySensor)`: `ClassCastException ✓` (green circle)
- `s.reading()`: `NullPointerException` (red circle)

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...

```

Annotations on slide 55:

- `device.sensor`: `NullPointerException ✓` (green circle)
- `(MySensor)`: `ClassCastException ✓` (green circle)
- `s.reading()`: `NullPointerException ✓` (green circle)

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Detecting Runtime Errors

```

...
if (device instanceof MyDevice)
{
  MySensor s = (MySensor) device.sensor;
  int value = s.reading();
  ...
}
...


```

Annotations on slide 56:

- `device.sensor`: `NullPointerException ✓` (green circle)
- `(MySensor)`: `ClassCastException ✓` (green circle)
- `s.reading()`: `NullPointerException ✓` (green circle)

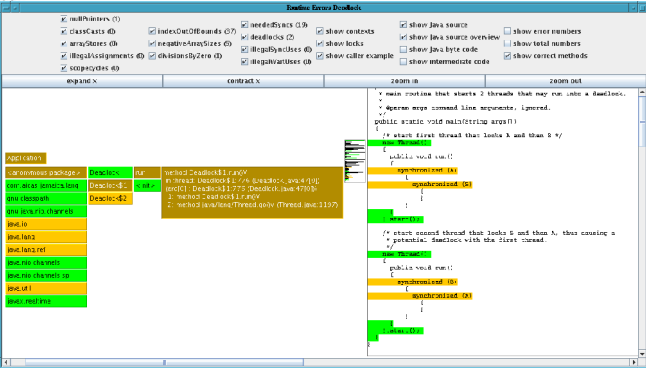
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Data Flow Analysis Tool



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Model Checking

- Numerous Tools (e.g. SPIN, PROSPER, Uppaal)
- Used to check some extracted attribute of a program or program model
- Bases on state machines
 - Limited computational power
 - Subject to state explosion
- Good for state machine like programs or network traffic
- Limited value for checking complex algorithms

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Deductive Formal Verification

- Formal Specifications
 - Preconditions
 - Postconditions
 - Invariants
- Runtime Tools (JML)
 - Jmlc
 - Daikon
- Liskov Substitution Principle
 - Defines a proper subtype
 - subclass = subtype
- Verification Tools
 - ESC/Java2 (Simplify)
 - JACK (B-Method, Simplify, PVS, Coq)
 - KeY (Dynamic Logic)

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The JamaicaVM Solution

Conclusion

- Java technology offers significant advantages over alternative languages for critical systems.
- Standard IDE, debugging, and analysis tools ease development.
- Realtime garbage collection with RTSJ enables deterministic device control.
- Wide variety of tools available
- Standards are emerging for supporting certification to the highest level.

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